A Real Time Instruction Extractor from Traffic Signal for Translation

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Abstract

This paper has developed and demonstrated a system to build traffic instruction detection and translation tools that can extract and convert Bangla text from natural images containing traffic instruction. In the process of developing the system, we have applied various techniques to extract and convert information from natural images. These techniques involve Image Processing, Machine Learning, Optical Character Recognition and Machine Translation. The proposed system consists of three steps, which are Text extraction from image, Post Processing by Language Model and Machine Translation.

Keywords: Optical Character Recognition, Image Processing, Machine Translation, Language Model

Résumé

Le papier [1] a proposé un système novateur pour la détection et la traduction automatique de textes sur des signaux de route. Les auteurs ont proposé un système de leur travail, qui est capable de définir une zone de recherche dans l'image. Le papier [2] a recommandé un système qui peut détecter et reconnaître les instructions de signalisation de route. Les auteurs de ce papier ont proposé un système pour intégrer dans le système de l'Advanced Driver Assistance System (ADAS). Nous avons reconnu et implémenté des techniques expressées et illustrées dans ce papier. De plus, nous avons incorporé des techniques supplémentaires pour améliorer le résultat de la reconnaissance des caractères Bangla OCR. Ces techniques comprennent la détection d’arêtes en utilisant le réseau nerveux Canny [3], le filtre gaussien [4], le suivi d’arêtes en utilisant la hystérésis [5], le labeling en noir et blanc, la segmentation de caractères [6], la reconnaissance de caractères à travers le réseau neuronal par propagation en arrière [7] pour traiter le texte extrait de l'image et l'algorithme de Machine Translation Example Based [8].

Notre méthode proposée pour la détection et la traduction du Bangla signalisation des signaux est composée de trois étapes. La première étape détecte les signaux de route des images naturelles. En conséquence, la deuxième étape extrait du texte Bangla de l’image naturelle. À la dernière étape, le texte est traduit en anglais. Ce papier représente le premier aventure en développant une détection de signaux de route et un système de traduction pour le langage Bangla. Bien que Google et Bing aient des produits similaires, ils ne disposent pas de support pour le Bangla OCR.

2. Previous Study

There are many works for Bangla OCR from documents like Bangla OCR by UIU and first commercial OCR “Puthi OCR” by Team Engine. Most prominently there are two notable thesis work for Bangla OCR from image. The first one is from Khulna University by Zahid et.al and other one is from Computer Vision & Pattern Recognition Unit,
Indian Stat. Inst., Kolkata, India. In this research, we have incorporated techniques analyzed from the above-mentioned sources and combined them into a single system application.

3. Proposed System

The proposed system processes the captured images and converts them into English instructions. Distinct modules of the system execute in sequence to acquire the targeted goal from the input. Each of these modules employs diversified tools and contemporary algorithms. These modules are explained with demonstration and relevant diagrams in the following section. The proposed system is illustrated in the system diagram in Figure 2.

3.1 Image Processing

Captured image that contains Bangla traffic instruction is processed through a sequence of techniques, which are clarified by demonstration in the following sub sections.

3.1.1 Pre-Processing

After the natural image is captured, the preprocessing mechanism is conducted on the image. The input and output of the process is illustrated in Figure 3.

Preprocessing resizes and adjusts the RGB value of the captured images. The outcome of this stage is the B/W image with the corrected proportion.

3.1.2 Pre-Filtering

On completion of the preprocessing pre-filtering is applied on the processed image. The pre-filtering of the image is conducted by employing Edge Detection by Canny Edge Detection Method. The Canny Method is less likely than other methods to be fooled by noise. The general criteria for edge detection include the following steps.

I. Detection of edge with low error rate, which means that the detection should accurately catch as many edges shown in the image as possible.

II. The edge point detected from the operator should accurately localize on the center of the edge.

III. A given edge in the image should only be marked once, and where possible, image noise should not create false edges.

After edge detection process is conducted, Gaussian filter [4] is applied on the output to further fine-tune the detected edges. The equation for a Gaussian filter kernel with the size of \((2k+1) \times (2k+1)\) is shown as following:

\[
H_{ij} = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{(i-k-1)^2 + (j-k-1)^2}{2\sigma^2}\right)
\]

Here is an example of a 5x5 Gaussian filter, used to create the image to the right, with \(\sigma = 1.4\). Here the asterisk denotes a convolution operation.

\[
B = \frac{1}{159} \begin{bmatrix}
2 & 4 & 5 & 4 & 2 \\
4 & 9 & 12 & 9 & 4 \\
5 & 12 & 15 & 12 & 5 \\
4 & 9 & 12 & 9 & 4 \\
2 & 4 & 5 & 4 & 2
\end{bmatrix} * A.
\]

After applying the filter, the intensity gradient of the image is established. The edge detection operator (Roberts, Prewitt, and Sobel for example) returns a value for the first derivative in the horizontal direction (Gx) and the vertical direction (Gy). From this, the edge gradient and direction can be determined by the following equations.

\[
G = \sqrt{G_x^2 + G_y^2}
\]

\[
\Theta = \tan^{-1}(G_y, G_x)
\]

In consequence, edge-thinning technique termed Non-maximum suppression is enforced on the produced output. After application of non-maximum compression, the edge pixels are quite accurate to present the real edge. However, there are still some edge pixels at this point caused by noise and color variation. In order to get rid of the spurious
responses from these bothering factors, it is essential to filter out the edge pixel with the weak gradient value and preserve the edge with the high gradient value. Thus, two threshold values are set to clarify the different types of edge pixels, one is called high threshold value and the other is called the low threshold value. On resolving the double threshold value, edge tracking is conducted by Hysteresis. Afterwards structural elements of the image are extracted and then dilated. On the completion of the above-mentioned processes, the cropped images are acquired. The cropped elements along with some garbage is illustrated in Figure 4.

![Cropped Elements after Pre-Filtering](image)

**Figure 4: Cropped Elements after Pre-Filtering.**

### 3.1.3 Filtering

Filtering techniques is further applied on the pre-filtered output. These techniques include range estimation of the pre-filtered output. In the mentioned process, the garbage elements are removed and actual Bangla texts from the image is revealed. The flow diagram of the filtering process is illustrated Figure 5.

![Flow Diagram of Filtering](image)

**Figure 5: Flow Diagram of Filtering.**

The output of this stage is illustrated in Figure 6.

![Filtered Image](image)

**Figure 6: Filtered Image.**

### 3.1.4 Character Segmentation

The character segmentation process segments the characters in two categories. The first category is Characters without KAR (Bangla _GENERALIZED_ARROW). The second category is characters with KAR.

![Characters without KAR](image)

**Figure 7: Characters without KAR.**

![Characters with KAR](image)

**Figure 8: Characters with KAR.**

Therefore, the final output will be like the illustration in Figure 9.

![Final Output of Character Segmentation](image)

**Figure 9: Final Output of Character Segmentation.**

As we train our NN with black letters which have white background so after segmenting those letters we simply reverse the black pixel with white pixels of each letters and the output is given in Figure 10.

![Output after Pixel Reversing](image)

**Figure 10: Output after Pixel Reversing.**

In addition, for better image processing we reshape the image into a constant height and width. We use 45 × 45 (= 2025) constant shapes for each letter. This output is illustrated in Figure 11.

![Characters after Reshaping](image)

**Figure 11: Characters after Reshaping.**

The flow diagram of the character segmentation is illustrated below in Figure 12.

![Flow Diagram of Character Segmentation](image)

**Figure 12: Flow Diagram of Character Segmentation.**

### 3.2 Character Recognition and Post-Processing

After segmentation process, the output must be converted into machine-readable text. Neural network is employed to generate that conversion. However, the output of the neural net may contain a few garbage, which must be eliminated
to extract clean text. The processes in Figure 12 are detailed in the following sub-sections.

3.2.1 Character Recognition Using BP ANN

Backpropagation Artificial Neural Network (BP ANN) is employed in the proposed system to convert the segmented characters into electronic text. The text is retrieved in Unicode font. Backpropagation (BP) artificial neural network is the most commonly used algorithm in OCR, as it is highly effective in the given context. A typical BP ANN is illustrated in Figure 13.

BP ANN employs the following technique to extract the electronic character from the character segmentation output, which is depicted in Figure 14.

3.2.2 Garbage Detection and Deletion

After character segmentation, post processing is conducted. Post processing is primarily consisted of garbage detection and deletion. To detect garbage from multi characters we will perform a partial string matching. Partial string matching is an approach to identify garbage value and useful to predict words from a partially correct word. Therefore, here is our algorithm:

- Split the result string.
- Iterate through all words.
- if(word.length > 1)
  Perform partial matching for each of the Bangla words in dictionary. Find the best matched Bangla words and return.

Afterwards Levenshtein’s Distance is employed to acquire best matching strings from the string dictionary. In figure 15 there is an illustration of an extracted charaqcter string with garbage values.

Figure 15: Sample Output with Garbage.

Now the first মষ in Figure 15 will be removed as that will not be partially matched with any word. গ in Figure 15 will also be removed, as it is a single character.

Instead of detecting সবে বাচ্চ our BP ANN returns সবে বাবষ because it will need three moves to transform one to another, which is minimum among other words in dictionary, and similarity between two words is 62%. Hence after post processing of the sample output we acquire the clean and authentic string as illustrated in Figure 16.

Figure 16: Output after Post Processing.

3.3 Machine Translation [8]

Now we have successfully extracted the authentic and clean text from the natural image. The next step is to convert the Bangla text into English. Machine Translation is a process of translating one word/sentence to another language’s corresponding word/sentence. Machine translation is a complex problem because there are thousands of things that are needed to be considered. In basic level, we can just replace the words in a sentence with corresponding word in target language. That is not able to produce a good translation as the sentence structures are different and the recognition of whole phrases with their closest counterparts in the target language is needed. The approach [8] that we have taken in this paper is illustrated in Figure 17.

This approach can successfully translate most of the common traffic instructions. However, the English meanings that are constructed using multiple Bangla words is not considered here. The process of our approach of machine translation is illustrated in the Figure 18. The translated output of the extracted Bangla text is shown in Figure 19.

Figure 17: Flow Diagram of Garbage Deletion Process.

Figure 14: Flow Diagram of Character Recognition

Figure 15: Extracted Character String with Garbage

Figure 16: Output after Post Processing

Figure 17: Flow Diagram of Machine Translation Process
4. Experimental Result and Analysis

The image of traffic instructions is very rare in internet. In fact, the traffic instructions are hard to find. Therefore, we really did not manage to get a plenty number of images for training and testing. That is one of the biggest difficulties that we have faced. Therefore, we have to test our system for limited training and testing data. Training Image Corpus: 22 and test corpus: 6. Backpropagation Artificial Neural Network is used where input features: 45×45 and output size: 18. Number of words in Traffic Instruction Database: 45. A demo corpus of pattern matching is shown in Table 1 and experimental result is shown in Table 2.

Table 1: Demo Corpus for Pattern Matching.

<table>
<thead>
<tr>
<th>Bangla Sentence</th>
<th>English Sentence</th>
</tr>
</thead>
<tbody>
<tr>
<td>পার্কিং নিষেধ</td>
<td>No parking</td>
</tr>
<tr>
<td>পথচারী চলাচল নিষেধ</td>
<td>No Pedestrian</td>
</tr>
<tr>
<td>সামনে টি.জাঁশন আছে</td>
<td>T-junction</td>
</tr>
<tr>
<td>সামনে পথচারী পারাপার</td>
<td>Pedestrian Crossing</td>
</tr>
</tbody>
</table>

5. Conclusion and Future Works

In this research work, state of the art algorithms to translate Bangla Traffic sign into English for Foreigners were implemented. Because Canny edge detection method is applied in the pre-filtering process to detect edges from the captured image, it will be less prone to get deceived by noise. Consequently, the system is able to analyze signs manipulated with rain, leaves and dirt and produce output that is quite accurate.

In the process of conducting the research work, we have identified a number of constraints and area of improvements. The most notable of them are listed as following.

- Limited Size of the training corpus
- Limitation of OCR for angled photos
- Image adjustment is not dynamic
- Overfitting of data from the Neural Network
- Machine translation needs optimization

Moreover, the authors would like to incorporate driver movement detection techniques through accelerometer, gyroscope and compass sensor data to align and compare that with the instruction from the traffic sign. Therefore, if the driver’s movement data is conceived as illegitimate according to the traffic signs, the system will generate a warning sound.

Table 2: Demo Experimental Result.

<table>
<thead>
<tr>
<th>Input Sentence Bangla</th>
<th>Output Sentence English</th>
</tr>
</thead>
<tbody>
<tr>
<td>সামনে সরু সেতু আছে</td>
<td>Narrow Bridge</td>
</tr>
<tr>
<td>সামনে গুলি</td>
<td>School</td>
</tr>
<tr>
<td>হ্যাপ্পটাল</td>
<td>Hospital</td>
</tr>
<tr>
<td>সামনে ওয়াइ-জাঁশন আছে</td>
<td>Y-Junction</td>
</tr>
<tr>
<td>খাদ্যনোনা নিষেধ</td>
<td>No Stopping</td>
</tr>
<tr>
<td>হল জানানা নিষেধ</td>
<td>No Horn Honking</td>
</tr>
<tr>
<td>সবোচ্চ গতিসীমা</td>
<td>Highest Speedlimit</td>
</tr>
<tr>
<td>বিপদজনক খাদ্য</td>
<td>Dangerous Dip</td>
</tr>
<tr>
<td>বনজজজন এলাকা</td>
<td>Picnic Site</td>
</tr>
</tbody>
</table>

References